# SOLVING DIFFERENTIAL EQUATION WITH SERIES EXPANSION TECHNIQUES

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### The Standard Model

- interactions;
- During the years it has proven itself very successful in explaining and predicting with **extreme precisions** a big variety of phenomena in fundamental interactions, spanning several orders of magnitude;
- The discovery of the Higgs boson in 2012 confirmed one of the most important predictions of the Standard Model.

#### The **Standard Model** is the best theory, so far, for describing the elementary particles and their





#### What's next?

- The SM has still many open questions, e.g. gravity, neutrino masses, dark matter, ...
- years;
- experimental measurements from theoretical predictions.



In order to appreciate, and then interpret through a dedicated analysis, such differences, we need theoretical predictions at least as accurate as the experimental value.

In order to answer those questions we need to find a model which goes **Beyond the Standard** Model (BSM). However, no experimental evidence of any BSM model has been found in the last

New physics effects could still enter in virtual corrections, leading to some deviations of







#### **Higher order corrections**

either in QCD or in EW;

LO 
$$\sigma^{(0,0)}$$
  $\gamma^{(0,0)}$   $\gamma^{(0,1)}$   $\gamma^{(0,1)}$ 

NNLO 
$$+\alpha_S^2 \sigma^{(2,0)} + \alpha_S \alpha \sigma^{(1,1)} + \alpha^2 \sigma^{(0,2)}$$

due to the high number of Feynman integrals with different energy scales;

In order to have more precise theoretical predictions we have to include higher order corrections,



One of the main bottlenecks in these calculations comes from the evaluations of virtual corrections



Process definition

 $\mathcal{O}(\alpha_S^2), \mathcal{O}(\alpha_S \alpha), \mathcal{O}(\alpha^2), \dots$ ►

Which particles are massless?



. . .

Process definition

Generation of Feynman diagrams

Some publicly available code: FeynArts or QGRAF



►

Process definition

Generation of Feynman diagrams

Computation of interference terms

- Simplifying expressions;
- Handling  $\gamma^5$  in d dimensions;
- Computing traces of  $\gamma$ -matrices;
- Reduce tensor loop-integrals to scalar ones;



Process definition

Generation of Feynman diagrams

Computation of interference terms

Reduce to a set of Master Integrals Publicly available code: KIRA, FIRE or REDUZE2, ...

$$\sum_{i=1}^{N} c_{i}I_{i} \longrightarrow \sum_{i=1}^{m} \tilde{c}_{i}MI_{i}, \quad m \ll N$$

Process definition

Generation of Feynman diagrams

Computation of interference terms

Reduce to a set of Master Integrals

Evaluation of MIs

Different approaches are possible: Feynman parameters, Monte Carlo integration, Tropical Geometry, ...

One possibility is the Method of **differential equations** (with a semi-analytical approach);

**Complex masses** for gauge bosons;

Process definition

Generation of Feynman diagrams

Computation of interference terms

Reduce to a set of Master Integrals

Evaluation of MIs

Subtraction of divergences

Counter-terms for **UV renormalisation**; Subtraction of **IR divergences**;

Process definition

Generation of Feynman diagrams

Computation of interference terms

Reduce to a set of Master Integrals

Evaluation of MIs

Subtraction of divergences

Production of a numerical grid



Create a **numerical grid**;

Combine with real contributions and perform a **Monte-Carlo** integration over phase-space;

Phenomenology

Process definition

Generation of Feynman diagrams

Computation of interference terms

Reduce to a set of Master Integrals

Evaluation of MIs

Subtraction of divergences

Production of a numerical grid



## **Evaluating Feynman integrals**

What we would like to compute are objects like this:



- family in terms a smaller subset, the so-called Master Integrals.



A given set of denominators  $\mathscr{D}_i$  constitutes an **integral family**. Inside an integral family an integral is uniquely identified by the set of the different powers  $\alpha_i$  to which the denominators are raised.

Using Integration by Parts (IBP) identities, we can express all the integrals of the given integral



### How to compute the Master Integrals?

- on the method of differential equations.
- **differential equations**, whose solution is the master integrals we are interested in.

$$\frac{\partial}{\partial s_k} I(\alpha_i; s_j, d) = \sum \text{ scalar integrals} = \sum \text{ master integrals}$$

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$$I(\alpha_i; s_j, d) = \sum \text{ scalar integrals} = \sum \text{ master integrals}$$

and homogeneous differential equations.

Many techniques have been developed during the years, each with pros and cons. Here I will focus

The idea is that by differentiating a master w.r.t. a kinematical invariants we obtain a first order linear

By repeating the same process for every master integral we obtain a system of first order linear



#### A very simple example: 1L bubble



$$I_{10} = \bigcup I_{11} =$$

By differentiating w.r.t.  $p^2$  we obtain

$$\frac{d}{dp^2} \quad \bigcirc \quad = 0$$

$$I_{\alpha_1 \alpha_2}(p^2, m^2, d) = \int \frac{d^d q}{i\pi^{d/2}} \frac{1}{\left[q^2 - m^2\right]^{\alpha_1} \left[(q - p)^2 - m^2\right]^{\alpha_2}}$$

This problem has **2 kinematic invariants**,  $p^2$  and  $m^2$ , and **2 master integrals**:  $I_{10}$  and  $I_{11}$ 





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This problem has 2 kinematic invariants,  $p^2$  and  $m^2$ , and 2 master integrals:  $I_{10}$  and  $I_{11}$ 



$$-\frac{(d-4)p^2 + 4m^2}{2p^2(4m^2 - p^2)} - O$$

### What are we looking for?

- So we just have to solve a system of first order differential equations... HOW?
- Ideally, we would like:
  - A method easy to automatise
  - A solution **compact and easy to handle** to allow for simplifications

- A solution fast to evaluate to be implemented in a Monte-Carlo
- To have high control on numerical precision

$$\mathcal{O}(10-10^2)$$
 2Re $\mathcal{M}^{(2)}$ 





 $\mathscr{M}^{(0)*} = \sum c_i M I_i \qquad \mathscr{O}(10^{-10} - 10^{10})$ 



### Analytical solution

- There are many possibilities to solve the system, each with pros and cons
- The first method is to solve it **analytically**. This is, by far, the preferable method.

$$I_{1,1}^{(finite)}(p^2, m^2) = 2 - \gamma_E - \log m^2 + \frac{m^2}{p^2} \left(\frac{1}{r} - r\right) \log r \qquad \text{with} \qquad r = \frac{-p^2 + 2m^2 + \sqrt{(p^2 - 2m^2)^2 - 4m^4}}{2m^2}$$

Generalised PolyLogarithms. Of these functions we know functional relations and series expansion;

$$G(a_1, ..., a_n; z) = \int_0^z \frac{dt}{t - a_1} G(a_2, ..., a_n; z) \quad and \quad G(\overrightarrow{0_n}; z) = \frac{1}{n!} \log^n z$$

might require a long time with external libraries.

The result is provided in closed form as a combination of elementary and special functions, such as

However, especially when increasing the number of scales or legs, an analytical expression in terms of known classes of functions might not be available. Moreover, the numerical evaluation of the result



#### Numerical solution

numerical grid.

$$I_{1,1}^{(finite)}(p^2, m^2 = 1)$$

numerical precision of the solution.





This can be done with methods such as Runge-Kutta. There are some examples in literature, however this has not received too much attention. The main problem is the difficulty in controlling the



#### **Semi-analytical solution**

a power series which can be easily evaluated in every point of the domain.

$$I_{1,1}^{(finite)}(p^2, m^2 = 1) = -\gamma_E + \frac{1}{6}p^2 + \frac{1}{60}(p^2)^2 + \frac{1}{420}(p^2)^3 + \frac{1}{2520}(p^2)^4 + \frac{1}{13860}(p^2)^5 + \dots$$

- variable [F.Moriello, arXiv:1907.13234], [M.Hidding, arXiv:2006.05510]
- The main advantage is that all the calculations can be carried out analytically.
- a negligible amount of time.
- analytic continuation of the solution must be provided.

A third possibility could be to use a **semi-analytical approach**. In this case the result is provided as

The method has been firstly implemented in the Mathematica package **DiffExp** for a real kinematic

This method is quite easy to automatise. Provided that we have infinite time and space, we could achieve arbitrary precision. Moreover, once we have the solution, it can be evaluated numerically in

However, series have a limited radius of convergence, hence, an algorithm for performing the







The singularities of the problem can be read from the coefficient matrix. 

$$I_{n_1 n_2 n_3} = \int \frac{d^d q}{i \pi^{d/2}} \frac{1}{\left[q^2\right]^{n_1} \left[(q+p_1)^2 - m_e^2\right]^{n_2} \left[(q-p_2)^2 - m_e^2\right]^n}$$

This problem has 2 masters, which can be chosen as the massive tadpole and the scalar triangle;

$$\frac{\epsilon - 1}{s m_e^2 (s - 4m_e^2)} B_1 + \frac{2m_e^2 - s - s\epsilon}{s (s - 4m_e^2)} B_2$$



- parameters the problem depends on, thus speeding up the computation.
- the minimum order in  $\epsilon$ , and write  $B_i = \sum B_i^{(j)} \epsilon^j$ . Then we can collect order by order in  $\epsilon$ :  $j = \epsilon_{min}$

$$\mathcal{O}(1/\epsilon) : \frac{\frac{d}{dx}B_1^{(-1)} = 0}{\frac{d}{dx}B_2^{(-1)} = -\frac{1}{x(x-4)}B_1^{(-1)} - \frac{x-2}{x(x-4)}B_2^{(-1)}}$$

U dx

For simplicity we introduce an **adimensional variable**  $x = s/m_{e}^{2}$ . This reduces the number of

The first step is to separate each order in  $\epsilon$ . To do so we can read from the boundary conditions

$$B_1^{(0)} = 0$$
  
$$B_2^{(0)} = \frac{1}{x(x-4)} B_1^{(-1)} - \frac{1}{x(x-4)} B_1^{(0)} - \frac{1}{x-4} B_2^{(-1)} - \frac{x-2}{x(x-4)}$$



use the ansatz  $B_2^{(-1),hom}(x) = x^r \sum c_i x^i$ , with  $r \in \mathbb{Q}$ . i=0

 $x^{r} | c_{1} + 2xc_{2} + 3x$ 

 $B_2^{(-1)}(0) = \frac{1}{2}$ 

$$\begin{aligned} x^{2}c_{3} + \mathcal{O}(x^{3})] + rx^{-1+r} \left[c_{0} + xc_{1} + x^{2}c_{2} + \mathcal{O}(x^{3})\right] &= \frac{x-2}{x(x-4)} \\ &= \left[\frac{1}{8} - \frac{1}{2x} + \frac{x}{32} + \frac{x^{2}}{128} + \mathcal{O}(x^{3})\right] x^{r} \left[c_{0} + xc_{1} + x^{2}c_{2} + \mathcal{O}(x^{3})\right] \end{aligned}$$

Let us start from  $\mathcal{O}(1/\epsilon)$  and expand around x = 0. The first equation is trivial and gives:  $B_1^{(-1)}(x) = 1$  $\frac{d}{dx}B_2^{(-1)}(x) = -\frac{x-2}{x(x-4)}B_2^{(-1)}(x) - \frac{1}{x(x-4)}$ 

First of all we start from the homogeneous equation. For that we use the Frobenius method, i.e. we

Let us expand everything

$$r c_0 x^{-1+r} + (1+r) c_1 x^r + (2+r) c_2 x^{1+r} + (3+r) c_3 x^{2+r} + \mathcal{O}(x^{3+r}) = \\ = -\frac{c_0}{2} x^{-1+r} + \left(\frac{c_0}{8} - \frac{c_1}{2}\right) x^r + \frac{1}{32} \left(c_0 + 4c_1 - 16c_2\right) x^{1+r} + \frac{1}{128} \left(c_0 + 4c_1 + 16c_2 - 64c_3\right) x^{2+r} + \mathcal{O}(x^{3+r}) = \\ = -\frac{c_0}{2} x^{-1+r} + \left(\frac{c_0}{8} - \frac{c_1}{2}\right) x^r + \frac{1}{32} \left(c_0 + 4c_1 - 16c_2\right) x^{1+r} + \frac{1}{128} \left(c_0 + 4c_1 + 16c_2 - 64c_3\right) x^{2+r} + \mathcal{O}(x^{3+r}) = \\ = -\frac{c_0}{2} x^{-1+r} + \left(\frac{c_0}{8} - \frac{c_1}{2}\right) x^r + \frac{1}{32} \left(c_0 + 4c_1 - 16c_2\right) x^{1+r} + \frac{1}{128} \left(c_0 + 4c_1 + 16c_2 - 64c_3\right) x^{2+r} + \mathcal{O}(x^{3+r}) = \\ = -\frac{c_0}{2} x^{-1+r} + \left(\frac{c_0}{8} - \frac{c_1}{2}\right) x^r + \frac{1}{32} \left(c_0 + 4c_1 - 16c_2\right) x^{1+r} + \frac{1}{128} \left(c_0 + 4c_1 + 16c_2 - 64c_3\right) x^{2+r} + \mathcal{O}(x^{3+r}) = \\ = -\frac{c_0}{2} x^{-1+r} + \left(\frac{c_0}{8} - \frac{c_1}{2}\right) x^r + \frac{1}{32} \left(c_0 + 4c_1 - 16c_2\right) x^{1+r} + \frac{1}{128} \left(c_0 + 4c_1 + 16c_2 - 64c_3\right) x^{2+r} + \mathcal{O}(x^{3+r}) = \\ = -\frac{c_0}{2} x^{-1+r} + \left(\frac{c_0}{8} - \frac{c_1}{2}\right) x^r + \frac{1}{32} \left(c_0 + 4c_1 - 16c_2\right) x^{1+r} + \frac{1}{128} \left(c_0 + 4c_1 + 16c_2 - 64c_3\right) x^{2+r} + \mathcal{O}(x^{3+r}) = \\ = -\frac{c_0}{2} x^{-1+r} + \frac{c_0}{2} x^{-1+r} + \frac{c$$

• And collect the different powers of x:

$$r c_{0} = -\frac{1}{2}c_{0}$$

$$(1+r) c_{1} = \frac{1}{8} - \frac{c_{1}}{2}$$

$$(2+r) c_{2} = \frac{1}{32} (1+4c_{1}-16c_{2})$$

$$(3+r) c_{3} = \frac{1}{128} (1+4c_{1}+16c_{2}-64c_{3})$$



$$r = -\frac{1}{2}$$

$$c_1 = \frac{1}{8}c_0$$

$$c_2 = \frac{3}{128}c_0$$

$$c_3 = \frac{5}{1024}c_0$$



#### Variation of parameters

method of variation of parameters, i.e. we look for a particular solution of the form:  $B_2^{(-1),part}(x) = C(x) B_2^{(-1),hom}(x)$ . If we substitute in the original equation we get

$$C'(x) B_2^{(-1),hom}(x) + C(x) B_2^{(-1),hom'}(x) = -\frac{x-2}{x(x-4)} C(x) B_2^{(-1),hom}(x) - \frac{1}{x(x-4)} C(x) -$$

$$C'(x) B_2^{(-1),hom}(x) = -\frac{1}{x (x-4)}$$

$$C(x) = \int_0^x -\frac{1}{x'(x'-4)} \left(B_2^{(-1),hom}(x')\right)^{-1} dx'$$

Now that we have a solution to the homogeneous equation we can obtain a particular one with the

$$C'(x) = -\frac{1}{x(x-4)} \left( B_2^{(-1),hom}(x) \right)^{-1}$$

$$B_2^{(-1),part}(x) = B_2^{(-1),hom}(x) \int_0^x -\frac{1}{x'(x'-4)} \left( B_2^{(-1),hom}(x') \right)^{-1} dx'$$



Now we can expand everything and integrate. Note that since we are expanding in x, all the integrals are trivial.

$$B_{2}^{(-1),part}(x) = c_{0} x^{-1/2} \left( 1 + \frac{1}{8}x + \frac{3}{128}x^{2} + \frac{5}{1024}x^{3} + \mathcal{O}(x^{4}) \right) \times \begin{bmatrix} -\frac{1}{x'(x'-4)} & \left( B_{2}^{(-1),hom}(x) \right)^{-1} \\ B_{2}^{(-1),hom}(x) & \times \int_{0}^{x} \left[ \frac{1}{4x'} + \frac{1}{16} + \frac{x'}{64} + \frac{x^{2}}{256} + \frac{x^{3}}{1024} + \mathcal{O}(x^{'4}) \right] \left[ c_{0}^{-1} x^{'1/2} \left( -\frac{x'}{8} - \frac{x^{2}}{128} - \frac{x^{3}}{1024} + \mathcal{O}(x^{'4}) \right) \right] dx' \\ = \frac{1}{2} + \frac{x}{12} + \frac{x^{2}}{60} + \frac{x^{3}}{280} + \mathcal{O}(x^{4})$$

$$B_2^{(-1)}(x) = c \ B_2^{(-1),hom}(x) + B_2^{(-1),part}(x) = c \ x^{-1/2} \left( 1 + \frac{x}{8} + \frac{3x^2}{128} + \frac{5x^3}{1024} + \mathcal{O}(x^4) \right) + \left( \frac{1}{2} + \frac{x}{12} + \frac{x^2}{60} + \frac{x^3}{280} + \mathcal{O}(x^4) \right)$$

The **complete solution** is obtained by combining the homogeneous one with the particular one.



$$B_2^{(-1)}(x) = c \ x^{-1/2} \left( 1 + \frac{x}{8} + \frac{3x^2}{128} + \frac{5x^3}{1024} + \mathcal{O}(x) \right)$$
$$= \frac{1}{2} + \frac{x}{12} + \frac{x^2}{60} + \frac{x^3}{280} + \mathcal{O}(x^4)$$

- From the differential equations we read the position of the singularities: x = 0 and x = 4. Since the series is centred in x = 0, this translate to the fact that the solution converges inside the interval (-4,4);
- We will come back later on the analytic continuation.



-0.5

-1.0

Re ····· Im



#### Logarithmic expansion

- In the previous case we expanded on x = 0, which was a possibly singular point, however, the solution was regular. That means that x = 0 is a **pseudo-threshold**.
- solution is a simple **Taylor series**.
- could contain terms like:

$$\frac{1}{x-4}$$
 or

These terms could arise from variation of parameters method. In particular:  $f^{part}(x) = f^{hom}(x) \left[ \int_{0}^{x} g^{non\ hom}(x') \left( f^{hom}(x') \right)^{-1} dx' \right]$ 

could contain either  $1/x^m$  with m > 1 or 1/x. At higher order in  $\epsilon$ ,  $g^{non\ hom}(x)$  may directly contains  $\log$ .

We could have expanded around a regular point. In this case we always have  $r \ge 0$ , hence, the

Another possibility is to expand on top of a **threshold**, e.g. in the 1L-QED vertex, x = 4. The solution

$$log(x-4)$$



#### Logarithmic expansion

For example, if we try to solve the order  $\mathcal{O}(\epsilon^0)$  of the same problem, but this time around x = 4, we get:

 $B_2^{(0)}(x) = 1.28861 - 0.18699 (x - 4) + 0.0357314$ 

$$+\frac{1}{\sqrt{x-4}}\left(-(4.9348+0.906688i)\right) + (0)$$

+(0.024095')

$$+\frac{\log(x-4)}{\sqrt{x-4}}\left(-1.5708i + 0.19635i(x-4) - 0.0368155i(x-4)^{2} + 0.0076699i(x-4)^{3} + \mathcal{O}(x-4)^{4}\right)$$



$$4 (x-4)^2 - 0.00748665 (x-4)^3 + \mathcal{O}(x-4)^4 +$$

0.61685 + 0.113336i (x - 4) +

$$7 + 0.00442719i$$
)  $(x - 4)^3 + O(x - 4)^4$ ) +

### **Triangle systems**

which it has the following form:

$$\frac{d}{dx} \begin{pmatrix} B_1 \\ B_2 \\ B_3 \\ \vdots \\ B_n \end{pmatrix} = \begin{pmatrix} \star & 0 \\ \star & \star \\ \star & \star \\ \vdots \\ \star & \star \\ \vdots \\ \star & \star \end{pmatrix}$$

equations.

With this approach we can solve all the systems which are in triangular form, i.e. those systems for

$$\begin{array}{cccc} 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \star & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ \star & \star & \cdots & \star \end{array} \begin{pmatrix} B_1 \\ B_2 \\ B_3 \\ \vdots \\ B_n \end{pmatrix}$$

The idea, hence, is to start from the lowest order in  $\epsilon$ , solve the first equation, substitute the result in the second and so on. Practically, instead of solving an  $n \times n$  system, we are solving n single

Frobenius method. Let us consider for example the following system:

$$B_1'(x) = \frac{B_1(x)}{x} - \frac{3B_2(x)}{x} + \left(\frac{1}{2} - \frac{9}{x}\right)$$
  
$$B_2'(x) = -\frac{2(x-3)B_1(x)}{x(x-9)(x-1)} + \frac{2(5x-9)B_2(x)}{x(x-9)(x-1)} - \frac{648 + (4\pi^2 - 273)x + 27x^2}{12x(x-9)(x-1)}$$

following ansatz:

$$B_1(x) = (x - 1)$$

$$B_1(x) = (x-1)^r \sum_{i=0}^{\infty} a_i (x-1)^i$$
$$B_2(x) = (x-1)^r \sum_{i=0}^{\infty} b_i (x-1)^i$$

Obtaining a system in a triangular form is not always possible, especially if the problem has an elliptic nature. In order to solve the homogeneous system of equation we have to use a generalisation of

Let us start from solving the homogeneous part of the system around x = 1. To do so let us use the



Let us substitute and collect order the different orders in (x - 1): 

$$\mathcal{O}\left(\frac{1}{x-1}\right) : \begin{cases} r a_0 = 0 \\ \frac{a_0}{2} - b_0 + rb_0 = 0 \end{cases} \qquad \mathcal{O}\left(x-1\right)^0 : \begin{cases} -a_0 + a_1 + r a_1 + 3 b_0 = 0 \\ \frac{1}{16}\left(-11 a_0 + 8 a_1 + 34 b_0 + 16 r b_1\right) = 0 \end{cases}$$

$$\{r = 0, a_0 = 2b_0\} \qquad \mathcal{O}\left(x-1\right) : \begin{cases} a_0 - a_1 + 2 a_2 + r a_2 - 3 b_0 + 3 b_1 = 0 \\ \frac{1}{128}\left(85 a_0 - 88 a_1 + 64 a_2 - 254 b_0 + 272 b_1 + 128 b_2 + 128 r b_2\right) = 0 \end{cases}$$

Now we can solve all the systems and we find a solution: 

$$B_1^{hom}(x) = a_1 \left( (x-1)^2 - \frac{5(x-1)^3}{4} + \frac{87(x-1)^4}{64} - \frac{91(x-1)^5}{64} + \mathcal{O}(x-1)^6 \right)$$
  
$$B_2^{hom}(x) = a_1 \left( -\frac{2(x-1)}{3} + \frac{11(x-1)^2}{12} - \frac{47(x-1)^3}{48} + \frac{97(x-1)^4}{96} - \frac{3161(x-1)^5}{3072} + \mathcal{O}(x-1)^6 \right)$$

$$\mathcal{O}(x-1)^0 : \begin{cases} -a_0 + a_1 + r a_1 + 3 b_0 = 0\\ \frac{1}{16} \left( -11 a_0 + 8 a_1 + 34 b_0 + 16 r b_1 \right) = \end{cases}$$

0

The solution we found to the homogeneous equation depends on **1** arbitrary constant  $a_1$ : 

$$B_1^{hom}(x) = a_1 \left( (x-1)^2 - \frac{5(x-1)^3}{4} + \frac{87(x-1)^4}{64} - \frac{91(x-1)^5}{64} + \mathcal{O}(x-1)^6 \right)$$
  
$$B_2^{hom}(x) = a_1 \left( -\frac{2(x-1)}{3} + \frac{11(x-1)^2}{12} - \frac{47(x-1)^3}{48} + \frac{97(x-1)^4}{96} - \frac{3161(x-1)^5}{3072} + \mathcal{O}(x-1)^6 \right)$$

the ansatz we chose was not general enough. Let us consider, hence:

$$B_1(x) = (x-1)^r \sum_{i=0}^{\infty} a_i (x-1)^i + \log(x-1) (x-1)^r \sum_{i=0}^{\infty} c_i (x-1)^i$$
$$B_2(x) = (x-1)^r \sum_{i=0}^{\infty} b_i (x-1)^i + \log(x-1) (x-1)^r \sum_{i=0}^{\infty} d_i (x-1)^i$$

However, this is a  $2 \times 2$  system and so we expected 2 linearly independent solutions! This is because

The procedure is the same, the only difference is that now we collect also powers of  $(x-1)^m \log(x-1)$ 

$$\mathcal{O}\left(\frac{\log(x-1)}{x-1}\right) : \begin{cases} r c_0 = 0\\ \frac{1}{2}\left(c_0 - 2 d_0 + 2 r d_0\right) = 0\\ \end{cases}$$

And the final solution is 

$$B_{1}^{hom}(x) = a_{0} \left[ 1 - \frac{x-1}{2} + \frac{9(x-1)^{3}}{128} + \mathcal{O}(x-1)^{4} + \left( \frac{3(x-1)^{2}}{16} - \frac{15(x-1)^{3}}{64} + \mathcal{O}(x-1)^{4} \right) \log(x-1) \right] + \\ + a_{2} \left( (x-1)^{2} - \frac{5(x-1)^{3}}{4} + \mathcal{O}(x-1)^{4} \right);$$

$$B_{2}^{hom}(x) = a_{0} \left[ \frac{1}{2} - \frac{x-1}{16} - \frac{7(x-1)^{2}}{128} + \frac{71(x-1)^{3}}{1024} + \mathcal{O}(x-1)^{4} + \left( -\frac{x-1}{8} + \frac{11(x-1)^{2}}{64} - \frac{47(x-1)^{3}}{256} + \mathcal{O}(x-1)^{4} \right) \log(x-1) \right] + \\ a_{2} \left( -\frac{2(x-1)}{3} + \frac{11(x-1)^{2}}{12} - \frac{47(x-1)^{3}}{48} + \mathcal{O}(x-1)^{4} \right)$$

$$\mathcal{O}\left(\frac{1}{x-1}\right) : \begin{cases} r a_0 + c_0 = 0\\ \frac{1}{2} \left(a_0 - 2 b_0 + 2 r b_0 + 2 d_0\right) = 0 \\ = 0, c_0 = 2d_0 \end{cases}$$

We can organise it in a matrix:  $\vec{B}^{hom}(x) = \mathbf{A}(x) \vec{c}$ . Where  $\mathbf{A}_{ij}(x)$  is the *i*-th solution, where we put all the constant to 0 except the *j*-th to 1. In this case  $\vec{c} = \begin{pmatrix} a_0 \\ a_2 \end{pmatrix}$ . We can use again the method of variation of parameters, now all quantities are matrices and vectors.

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- around x = 1, we have to integrate only terms like  $(x - 1)^m \log^n(x - 1)$ .
- ► boundary conditions:

$$B_1^{hom}(x) = \frac{59}{8} + \frac{\pi^2}{4} + \frac{3}{8}(x-1) + \frac{1}{4}(x-1)^2 - \frac{1}{3}(x-1)^3 + \frac{139}{384}(x-1)^4 + \mathcal{O}(x-1)^5$$
$$B_2^{hom}(x) = \frac{1}{2}\left(\frac{\pi^2}{6} - 1\right) + \frac{1}{4}(x-1)^2 - \frac{25}{96}(x-1)^3 + \frac{155}{576}(x-1)^4 + \mathcal{O}(x-1)^5$$

- quicker.
- types of physical problems, including the elliptic ones.

We can invert the matrix and perform the integration easily. Once again, by expanding  $\vec{g}^{non\ hom}(x)$ 

Finally, the general solution is  $\overrightarrow{B}(x) = \mathbf{A}(x) \ \overrightarrow{c} + \overrightarrow{B}^{part}(x)$ , and the constants are fixed using the

Since there is the inversion of a matrix if the system is not in triangular form, it is computationally more expensive to solve it. It might be worth to try to decuple the system so that the resolution is

### In principle with this approach we could solve any system of differential equations. Facing all

### **Boundary Conditions**

point;

$$f(x) = c \left( 1 - \frac{x}{5} - \frac{3x^2}{50} - \frac{11x^3}{750} + \mathcal{O}(x^4) \right) + \left( \frac{1}{2}x - \frac{7x^2}{40} + \frac{2x^3}{75} + \mathcal{O}(x^4) \right) \qquad f(0) = 1$$

The second is to **impose the regularity of the solution** in a pseudo-threshold point;

$$f(x) = c \ x^{-1/2} \left( 1 + \frac{x}{8} + \frac{3x^2}{128} + \frac{5x^3}{1024} + \mathcal{O}(x^4) \right) + \left( \frac{1}{2} + \frac{x}{12} + \frac{x^2}{60} + \frac{x^3}{280} + \mathcal{O}(x^4) \right)$$

$$f(x) = \frac{i\pi - ic + \log 2}{\sqrt{x - 4}} + \mathcal{O}(x - 4)$$

expansion by region.

The first one is to provide the value of the master integral in a regular or a pseudo-threshold

A third possibility is to impose the coefficient of the divergent part, such as  $\log x$  or  $1/x^m$ .

$$f(0) = \frac{\log 2}{\sqrt{x - 4}} + \mathcal{O}(x - 4)$$

The boundary conditions are, in general, **not trivial to obtain**. Some common techniques are the Auxiliary mass flow method, direct integration outside of the physical region, Monte-Carlo integration,



#### **Complex Mass Scheme**

- and Z. In this case, it is useful to perform the calculations in the **complex-mass scheme**;
- For these particles we consider their mass to be complex-valued:

The complex mass scheme **regularises** the divergences coming from the tree-level propagators, while preserving gauge invariance.

 $s - m_V^2 + i\delta$ 



$$x = \frac{s}{m_V^2} \to \frac{s}{\mu_V^2}$$

- As we saw, the analytic continuation must be discussed in the entire complex plane
- Power series have a limited radius of convergence.
- The radius is determined by the position of the **nearest singularity**.



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## **Taylor vs Logarithmic**

When moving along an horizontal line, the Feynman prescription plays an important role 





When moving along an horizontal line, the **Feynman prescription** plays an important role 



 $s - m_V^2 + i\delta$ 

#### Automatic packages

- This idea was first introduced in the study of Higgs+jet production at 2-loop [F. Moriello, arXiv:1907.13234].
- The first publicly available Mathematica package implementing this technique is **DiffExp**
- Another Mathematica implementation is in the package **SeaSyde (TA**, R. Bonciani, S. Devoto, N. Rana, A. Vicini, arXiv:2205.03345]. For the first time we introduced the algorithm for the analytic continuation in the complex plane, thus allowing it to be used in **EW calculations**. For example it has been used for the calculation of NNLO mixed QCD-EW corrections to the Drell-Yan process.

[M.Hidding, arXiv:2006.05510]. The main limitation of DiffExp is the fact that it can work only with real-valued variables. For this reason, it is suitable with QCD calculations, but not for EW ones.



#### Automatic packages

obtaining the boundary conditions.

$$I_{aux}(\alpha_i; s_j, d, \eta) = \int \prod_{k=1}^l \frac{d^d q_k}{i\pi^{d/2}} \frac{1}{[\mathcal{D}_1 - \eta]^{\alpha_1} \dots [\mathcal{D}_n - \eta]^{\alpha_n}}$$

 $I_{aux}$  from  $\infty$  to  $i0^{-1}$ 

$$\frac{\partial}{\partial \eta} \vec{I}_{aux} = A(\eta) \vec{I}_{aux}$$

- All three packages can solve all type of problems, including elliptic ones.
- not public yet.

#### A third independent implementation is in the Mathematica package AMFlow IX. Liu, Y. Ma, arXiv:2201.11669]. In particular, they use the auxiliary mass flow method for automatically

In the limit  $\eta \to \infty$  the integrals simplify and thus they can be easily evaluated analytically. Then we can write down the differential equation w.r.t.  $\eta$ , and, finally, recover the desired integral by evolving

$$I = \lim_{\eta \to i0^-} I_{aux}(\eta)$$

A fourth group is working on a C++ implementation **LoopTransport** [T. Neumann], however, this is





#### Neutral-current Drell-Yan

The first physical application of SeaSyde was for the calculation of the mixed QCD-EW corrections for the **Neutral-Current Drell-Yan** [TA, R. Bonciani, S. Devoto, N.Rana, A.Vicini, arXiv:2201.01754]

$$\sigma^{(0,0)} + \alpha_S \sigma^{(1,0)} + \alpha \sigma^{(0,1)} + \alpha_S^2 \sigma^{(2,0)} + \alpha_S \alpha \sigma^{(1,1)} + \alpha^2 \sigma^{(0,2)} + \dots$$

We had **36 Master Integrals** with 2 internal (complex-)massive lines. For 31 out of 36 we had an expression in terms of Generalised PolyLogarithms (GPLs). However, for 5 of them we only had an expression in terms of Chen-Goncharov integrals, which are not suitable for a numerical evaluation.





#### Neutral-current Drell-Yan

- 31 masters provide cross checks with analytic results, 5 are a prediction;
- complex mass scheme smoothens the behaviour at threshold.



#### results, 5 are a prediction; iour at threshold.

### Neutral-current Drell-Yan

The boundary conditions are imposed in the **euclidean region**, outside of the physical one. terms in the series required.

Number of terms	Precision	Time
50 terms	10 <sup>-14</sup>	~14 min
75 terms	10 <sup>-19</sup>	~26 min
100 terms	10 <sup>-25</sup>	~50 min
125 terms	10 <sup>-33</sup>	~75 min
150 terms	10 <sup>-40</sup>	~90 min

Given the execution time it is impossible to implement directly in a Monte-Carlo generator. For this reason, we created a grid for the final correction and then, thanks to its smoothness we can interpolate it. The grid consist of 3250 point spanning  $\sqrt{s} \in [40 \text{ GeV}, 13 \text{ TeV}]$  and  $\cos \theta \in [-1,1].$ 



Transporting the solution to the physical region requires different times depending on the number of



## **Charged-current Drell-Yan**

- This process, even if similar to the previous one, is more complicated because now we have integrals with two different internal massive lines.
- Those integrals belong to a two-loop box integral family. In this family we have 56 masters. We could proceed in the same way as before, that is find the boundary conditions and then use the differential equations w.r.t. s and t to create a grid which covers the entire phase space.
- Another possibility is to write down the differential equations w.r.t. one of the two masses and use the grid of the neutral current Drell-Yan as a boundary condition.







#### Conclusion

- completely general. Moreover, we can easily control the numerical precision of the result;
- Monte-Carlo generator;
- handle arbitrary internal complex masses;
- Neutral current Drell-Yan and to the charged current case (not yet public).

The method of differential equations, and in particular its semi-analytical approach, is a powerful technique for evaluating Feynman integrals. In particular, it is a method easy to automatise and

Its main problem right now is the speed, mainly due to the fact that all its implementations are in Mathematica. For this reason we have to rely on pre-computed grids which are then interpolated in

We implemented the method in the publicly available Mathematica package SeaSyde, which can

The method has been already applied in the calculation of the mixed QCD-EW corrections to the

